Environmental Fluid Dynamics: Lecture 20

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1 Similarity Theory

Overview Buckingham Pi Theory Scaling Variables Monin-Obukhov Similarity Theory



Similarity Theory

- Goal: We want to describe physical processes in the ABL.
- Problem: We lack understanding of the underlying physics.
- Solution: Derive empirical relationships b/t ABL variables.
- Tool: Similarity theory group variables, create relationships.



- Similarity theory is based on placing variables into dimensionless groups.
- We will use Buckingham Pi theory to do this.
- The goal is to properly group the variables such that we can create universal relationships between them.



Four Steps to Develop Similarity Theory

- Choose relevant variables
- Organize variables into dimensionless groups
- Use experimental data to determine values of dimensionless groups
- Create bets-fit curve to describe the relationship between the variables



Similarity Theory

- Result is an empirical equation or curves that show the same shape (i.e., they look self-similar thus, similarity theory).
- We hope the result is universal so that we can apply it to other situations different to our experiment.
- The derived equations are called similarity relationships.
- These relationships are usually applied to steady-state situations.
- Think of similarity theory as a zero-order closure we can use them to diagnose values of mean wind, temperature, and moisture as a function of height without making any assumptions regarding turbulence closure



- Buckingham (1914) proposed a systematic approach for dimensional analysis.
- Buckingham Pi Theory represents an optimal approach to determine a dependent variable in a physical problem.
- If we can identify m-1 parameters that govern a dependent variable, and if n is the number of dimensions, then:
 - m-n independent dimensionless quantities (π groups) are formed (cannot be made from other π groups)
 - m n independent dimensionless quantities are functionally related so that the dependent variable can be taken as a function of the governing parameters.
- The requires a grasp of a problem's physics.



Buckingham Pi Theory - A procedure to group variables into dimensionless groups

- 1 Select variables relevant to the problem
- Prind the dimensions of each variables and express in terms of fundamental dimensions: (e.g., length, mass, time, temp.)
- **8** Count the number of fundamental dimensions
- Pick subset of the original variables as "key" variables, subject to these restrictions:
 - The number of key variables must be equal to the number of fundamental dimensions.
 - All fundamental dimensions must be represented in the key variables
 - No dimensionless group may be possible from any combination of the key variables



Buckingham Pi Theory - A procedure to group variables into dimensionless groups

- **6** Form dimensionless equations of the remaining variables in terms of the key variables
- Solve for powers of the terms in the equations to yield dimensionally consistent equations
- Oivide the left hand side of each equation by the right to get dimensionless (π) group. The number of π groups will always equal the number of variables minus the number of dimensions.



Buckingham Pi Theory: Example

Consider flow through a pipe. How does τ vary?

- We hypothesize that the important variables are fluid density, dynamic viscosity, velocity, shear stress, pipe diameter, and pipe roughness
- **2** The fundamental dimensions of these variables are:

fluid density	ho	${\rm M}~{\rm L}^{-3}$
dynamic viscosity	μ	${\rm M} {\rm L}^{-1} {\rm T}^{-1}$
velocity	U	$L T^{-1}$
shear stress	au	${\rm M} {\rm L}^{-1} {\rm T}^{-2}$
pipe diameter	D	\mathbf{L}
pipe roughness	z_0	\mathbf{L}



Consider flow through a pipe. How does τ vary?

- $\ensuremath{\mathfrak{S}}$ There are 3 fundamental dimensions: $\mathrm{M},\mathrm{L},\mathrm{T}$
- **4** We need 3 key variables. Let's choose ρ , D, and U.
- 6 Now we form dimensionless equations for $\mu,\,\tau,$ and z_0 in terms of $\rho,\,D,$ and U

$$\tau = \rho^a D^b U^c$$
$$\mu = \rho^d D^e U^f$$
$$z_0 = \rho^g D^h U^i$$



Consider flow through a pipe. How does τ vary?

6 Now we solve for the exponents. Let's look at τ :

$$\begin{split} \tau &= \rho^a D^b U^c \\ \mathrm{M} \ \mathrm{L}^{-1} \ \mathrm{T}^{-2} &= (\mathrm{M} \ \mathrm{L}^{-3})^a (L)^b (\mathrm{L} \ \mathrm{T}^{-1})^c \\ \mathrm{M} \ \mathrm{L}^{-1} \ \mathrm{T}^{-2} &= \mathrm{M}^a \ \mathrm{L}^{-3a+b+c} \ \mathrm{T}^{-c} \end{split}$$

We must match dimensions

$$M: 1 = a$$
 $L: -1 = -3a + b + c$ $T: -2 = -c$

We solve for the unknowns to yield:

$$a=1$$
 $b=0$ $c=2$



Consider flow through a pipe. How does τ vary?

6 Thus, our dimensionally consistent equation is:

$$\tau=\rho^1 D^0 U^2=\rho U^2$$

Similarly, we find that:

$$\mu = \rho U D \qquad z_0 = D$$

7 Now we divide the left by the right side to get our π groups

$$\pi_1 = \frac{\tau}{\rho U^2} \qquad \pi_2 = \frac{\mu}{\rho U D} \qquad \pi_3 = \frac{z_0}{D}$$

Note that π_1 is the drag coefficient C_D , π_2 is inverse Reynolds number Re, and π_3 is relative roughness.



- For similarity theory, we want variables that represent forcings on the boundary layer (e.g., fluxes).
- Some key variables appear often and are called scaling variables.
- Generally, we want one length scale, one velocity scale, and if needed a temperature/moisture scale (usually no time scale since it can be made from length and velocity scales).
- Some variables always appear grouped, which allows for the creation of new scaling variables based on their combination.



• Some common scaling variables for the atmosphere:

$$u_* = (-\overline{w'u'})^{1/2}$$
$$\theta_* = \frac{-(\overline{w'\theta'})}{u_*}$$
$$\theta_{v*} = \frac{-(\overline{w'\theta'})}{u_*}$$
$$q_* = \frac{-(\overline{w'\theta'})}{u_*}$$
$$b_* = \frac{-(\overline{w'b'})}{u_*}$$



• Let's consider the signs of these scaling variables depending on static stability:

$$\begin{split} \text{unstable} &\to \overline{w'b'} > 0, \partial b/\partial z < 0, b_* < 0\\ \text{neutral} &\to \overline{w'b'} = 0, \partial b/\partial z = 0, b_* = 0\\ \text{stable} &\to \overline{w'b'} < 0, \partial b/\partial z > 0, b_* > 0 \end{split}$$

• Notice how the scaling terms are aligned with the gradients.



- Theory developed for the atmosphere by Monin-Obukhov (1954) based on dimensional analysis.
- Monin-Obukhov Similarity Theory (MOST) suggests that there are four parameters governing quasi-steady-state turbulence immediately above a flat, horizontallyhomogeneous surface

$$\begin{split} \ell &= \kappa z & \quad \text{length scale of turbulence} \\ u_* & \quad \text{friction velocity} \\ B_0 &= \overline{w'b'} & \quad \text{buoyancy flux} \\ \partial \overline{u}/\partial z & \quad \text{velocity gradient} \end{split}$$

• Note: κ is the von Kármán "constant", which is a dimensionless constant of proportionality introduced to relate the turbulence length scale and height above the surface. A typical value is $\kappa = 0.4$.



It is also important to consider what we ignored:

- *boundary layer depth*: assume largest eddies do not greatly influence eddies near the surface
- *mean wind*: turbulence must be invariant to Galilean transformations, and the mean wind is not
- rotational effects: turbulence Coriolis force is very small
- molecular effects: turbulence Reynolds number is very large
- roughness elements z_0 : assume $z \gg z_0$



• The fundamental dimensions of our governing variables are:

turbulence length scale	ℓ	\mathbf{L}
friction velocity	u_*	$L T^{-1}$
buoyancy flux	B_0	$L^2 T^{-3}$
velocity gradient	$\partial \overline{u}/\partial z$	T^{-1}

- So we have m = 4 paramters and n = 2 dimensions.
- Accordingly, we expect to have $m n = 2 \pi$ groups.
- We take group as a non-dimensionalized dependent variable and the other as the independent variable.



- Let's fidn the non-dimensionalized dependent variable
- There are 2 fundamental dimensions: ${\rm L}, {\rm T}$
- We need 2 key variables. Let's choose u_* and κz .
- Form a dimensionless equation for $\partial \overline{u}/\partial z$ in terms of u_* and κz :

$$\partial \overline{u}/\partial z = u^a_* \ (\kappa z)^b$$

• Now we solve for the exponents.

$$\partial \overline{u} / \partial z = u_*^a (\kappa z)^b$$
$$T^{-1} = (L T^{-1})^a (L)^b$$
$$T^{-1} = L^{a+b} T^{-a}$$

We must match dimensions

$$L: 0 = a + b$$
 $T: -1 = -a$

We solve for the unknowns to yield:

$$a = 1$$
 $b = -1$



• Thus, our dimensionally consistent equation is:

$$\partial \overline{u}/\partial z = u_*^1 \ (\kappa z)^{-1}$$

• Now we divide the left by the right side to get our π groups

$$\pi_1 = \frac{\kappa z}{u_*} \frac{\partial \overline{u}}{\partial z}$$

 This represents the non-dimensional dependent variable (vertical gradient of velocity)



- Now, let's find the independent variable.
- There are 2 fundamental dimensions: ${\rm L}, {\rm T}$
- We need 2 key variables. Let's choose u_* and B_0 .
- Form a dimensionless equation for ℓ in terms of u_* and B_0 :

$$\ell = \kappa z = u_*^a B_0^b$$

• Now we solve for the exponents.

$$\begin{split} \kappa z &= u_*^a B_0^b \\ \mathbf{L} &= (\mathbf{L} \ \mathbf{T}^{-1})^a \ (\mathbf{L}^2 \ \mathbf{T}^{-3})^b \\ \mathbf{L} &= L^{a+2b} \ T^{-a-3b} \end{split}$$

We must match dimensions

$$L: 1 = a + 2b$$
 $T: 0 = -a - 3b$

We solve for the unknowns to yield:

$$a = 3$$
 $b = -1$



• Thus, our dimensionally consistent equation is:

$$\kappa z = u_*^3 \ B_0^{-1}$$

• Now we divide the left by the right side to get our π groups

$$\pi_2 = \frac{\kappa z B_0}{u_*^3}$$

• Remember that we said some scaling variables always appear in a particular grouping? Here we define a new scaling variable called the Obukhov length,

$$L = -\frac{u_*^3}{\kappa B_0}$$

• Thus,

$$\pi_2 = -\frac{z}{L}$$



Aside: Obukhov Length

- |L| is interpreted as the height at which buoyancy effects become dynamically important.
- Neutral conditions: $L \to \infty \Rightarrow z/L = 0$
- Stable conditions: L > 0
- Unstable conditions: L < 0
- In the absence of surface stress (no mean flow), L = 0



• The two π groups are functionally related, thus

$$\frac{\kappa z}{u_*} \frac{\partial \overline{u}}{\partial z} = \phi_m \left(\frac{z}{L}\right)$$

where ϕ_m is a universal function of $\zeta=z/L$

• Similarly, we can show that

$$\frac{\kappa z}{\theta_*} \frac{\partial \overline{\theta}}{\partial z} = \phi_h(\zeta) \qquad \qquad \frac{\kappa z}{\theta_{v*}} \frac{\partial \overline{\theta_v}}{\partial z} = \phi_v(\zeta)$$
$$\frac{\kappa z}{\theta_*} \frac{\partial \overline{b}}{\partial z} = \phi_b(\zeta) \qquad \qquad \frac{\kappa z}{q_*} \frac{\partial \overline{q}}{\partial z} = \phi_q(\zeta)$$

Often we assume that $\phi_h=\phi_v=\phi_b=\phi_q$

• Thus, when normalized by $z, L, u_*, \theta_*, \theta_{v*}, b_*, q_*$, gradients of mean turbulent quantities are functions of only $\zeta = z/L!$



- We need formulations for our universal similarity functions
- Many empirical forms have been formulated using data from the famous 1968 Kansas experiment.

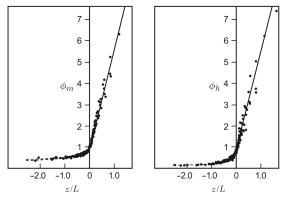


Figure 10.3 The M-O functions for mean wind shear (left) and mean potential temperature gradient (right), Eq. (10.12), from the 1968 Kansas experiment. From Businger *et al.* (1971).



From Wyngaard (2010)

• Although many forms exist, your professor prefers the functions proposed by Dyer (1974) because they are compact

$$\begin{array}{ll} \mbox{neutral} & \phi_m = 1 & \phi_h = 1 \\ \mbox{unstable} & \phi_m = (1 - 16\zeta)^{-1/4} & \phi_h = (1 - 16\zeta)^{-1/2} \\ \mbox{stable} & \phi_m = 1 + 5\zeta & \phi_h = 1 + 5\zeta \\ \end{array}$$

• Thus, MOST allows us to determine turbulent fluxes from the mean gradients

