#### Environmental Fluid Dynamics: Lecture 9

Dr. Jeremy A. Gibbs

Department of Mechanical Engineering University of Utah

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#### 1 Atmospheric Dynamics: Basic Equations Conservation of Momentum, continued



# Atmospheric Dynamics:

# Conservation of Momentum,

continued

- $\vec{F} = m\vec{a}$  is only valid for inertial (non-accelerating) reference frames.
- Note: a reference frame is not the same as a coordinate system because it depends on the motion of the observer.
- An inertial reference frame is stationary or it moves at a constant velocity.
- A non-inertial reference frame changes velocity or rotates.



- It is convenient to work with a reference frame that is fixed with respect to Earth.
- Why? This is how we take measurements.
- The Earth rotates, so this reference frame is non-inertial.
- How do we reconcile the limitations of Newton's 2<sup>nd</sup> Law?
- Fortunately, we can modify  $\vec{F} = m \vec{a}$  to allow for its application to non-inertial reference frames through the introduction of "apparent forces".

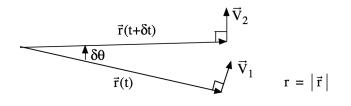


#### Conservation of Momentum: Apparent Forces

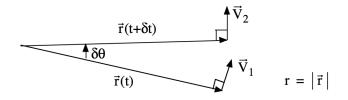
- There are two types of apparent forces that arise due to our rotating reference frame: *centrifugal* and *Coriolis*.
- **Centrifugal Force:** the inertial force on an object that is directed away from the axis of rotation that appears to act on all bodies when viewed in a rotating frame of reference.
- **Coriolis Force:** the inertial force that appears to act on an object in motion relative to a rotating frame of reference.



- Imagine some part of the universe that is not accelerating.
- We will put a reference frame (observer) there.
- It is an inertial reference frame, so  $\vec{F} = m\vec{a}$  is valid.
- Our observer sees a ball with mass m attached to a string spinning in a circle of radius r at constant angular velocity ω.
- What is ball's observed acceleration?
- Look at the ball at 2 infinitesimally close times t and  $t + \delta t$ .

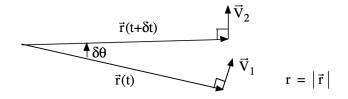






- $\omega = d\theta/dt \rightarrow$  thus, the angular displacement  $\delta\theta$  of the ball in time  $\delta t$  is:  $\delta\theta = \omega \delta t$ .
- The ball's speed  $\left| \vec{V} \right| = \omega r$  is constant since  $\omega$ , r are constant.
- Thus, only the direction of the ball's velocity changes.





• The vector change in  $\vec{V}$  over a tiny time increment is  $\perp$  to  $\vec{V}.$ 

 $\left| \vec{V} \right| = \text{constant} 
ightarrow \sqrt{u^2 + v^2} = \text{constant} 
ightarrow u^2 + v^2 = \text{constant}$ 

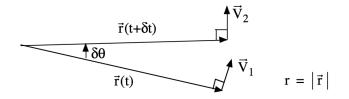
$$\rightarrow \vec{V} \cdot \vec{V} = \text{constant} \rightarrow \frac{D}{Dt} (\vec{V} \cdot \vec{V}) = \frac{D(\text{constant})}{Dt} = 0$$

$$\rightarrow \vec{V} \cdot \frac{D\vec{V}}{Dt} + \vec{V} \cdot \frac{D\vec{V}}{Dt} = 2\vec{V} \cdot \frac{D\vec{V}}{Dt} = 0$$

$$\vec{V} = \vec{D} \cdot \vec{D} \cdot$$

Since  $\vec{V} \neq 0$  and  $\frac{DV}{Dt} \neq 0$ , must have  $\vec{V} \perp \frac{DV}{Dt}$ 

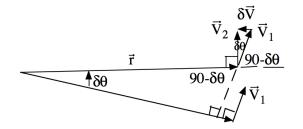




So, the change in \$\vec{V}\$ (acceleration) is perpendicular to \$\vec{V}\$
Another way to think about it: there can be no change in \$\vec{V}\$ in the direction of \$\vec{V}\$ since \$|\vec{V}|\$ is constant. If there was such an acceleration, then \$|\vec{V}|\$ would increase/decrease, which is impossible since it is constant. Thus, any change in \$\vec{V}\$ must be in the radial direction.



• We can see it graphically



For small  $\delta\theta$ ,  $\delta \vec{V}$  is perpendicular to  $\vec{V}$  ( $\vec{V_1}$  or  $\vec{V_2}$ ) - meaning it points toward the axis of rotation ( $-\hat{r}$  direction).



• In the previous example, consider a circle with radius ert ec V ert



$$\left|\delta \vec{V}\right| = \left|\vec{V}\right|\delta\theta = -\omega r\delta\theta \to \delta \vec{V} = -\omega r\delta\theta \hat{r}$$

divide bt  $\delta t$ 

$$\frac{\delta \vec{V}}{\delta t} = -\omega r \frac{\delta \theta}{\delta t} \hat{r}$$

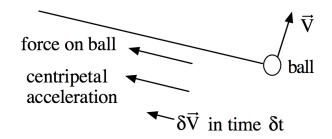
Take the limit as  $\delta t \rightarrow 0$ 

$$\frac{D\vec{V}}{Dt} = -\omega r \frac{D\theta}{Dt} \hat{r} = -\omega^2 r \hat{r} = -\omega^2 \vec{r}$$

Thus, the acceleration of the ball is inward toward to the axis of rotation and is called the centripetal acceleration.



• The force causing this centripetal acceleration is the string pulling inward on the ball:



• Can apply  $\vec{F} = m\vec{a}$  since we are in an inertial reference frame:

$$\vec{F}_{\rm on \ ball \ due \ to \ string} = -m\omega^2 \vec{r}$$



- Consider the same physical problem, but now our observer (reference frame) is now fixed with respect to the ball.
- The ball appears stationary in this non-inertial reference frame, so the apparent acceleration is 0.
- However, there is still a force on the ball due to the string!
- Applying Newton's 2<sup>nd</sup> Law in this non-inertial reference frame says F<sub>on ball due to string</sub> = 0 which is wrong since a force does exist.



- To make Newton's 2<sup>nd</sup> Law work in our non-inertial reference frame we need to introduce an "apparent" force that cancels with the force on the string.
- This apparent force is called the centrifugal force.

$$\vec{F}_{\rm on \ ball \ due \ to \ string} + \vec{F}_{\rm centrifugal} = 0$$

thus,

$$\vec{F}_{\text{centrifugal}} = -\vec{F}_{\text{on ball due to string}}$$
  
 $\vec{F}_{\text{centrifugal}} = m\omega^2 \vec{r}$ 

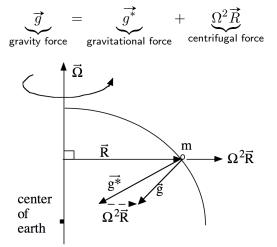


- Instead of a ball, consider a reference frame that is fixed with respect to Earth.
- Earth rotates with angular velocity  $\vec{\Omega}$  ( $\Omega \equiv \left| \vec{\Omega} \right|$ )
- Consider a mass m at rest on the surface of Earth,  $\vec{R}$  is the position vector of this mass with respect to the axis of rotation.
- We arrive at the centrifugal force per unit mass:

$$\frac{\overrightarrow{F}_{\rm centrifugal}}{m} = \Omega^2 \overrightarrow{R}$$



 We can now define the *effective gravity*, which is the sum of the fundamental gravitational force and the apparent centrifugal force:

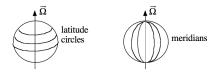




- We considered a mass at rest on Earth's surface.
- What happens if the mass is moving?
- We will need to introduce a second apparent force to enable the use of Newton's 2<sup>nd</sup> Law.
- This apparent force related to movement in the rotating reference frame is named after French scientist Gaspard-Gustave de Coriolis.



• Let's define velocity in terms of Earth



- u = velocity along a latitude circle
  - u > 0 toward east (westerly wind)
  - u < 0 toward west (easterly wind)
- v = velocity along a meridian
  - v > 0 toward north (southerly wind)
  - v < 0 toward south (northerly wind)
- w = vertical velocity
  - w > 0 upward motion
  - w < 0 downward motion



- Imagine that we kick an initially resting mass m toward the east.
- Since u > 0 here, the mass rotates faster than earth.
- The centrifugal force on the initially resting mass was:

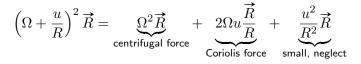
#### $\Omega^2 \vec{R}$

• The centrifugal force on the mass after being kicked:

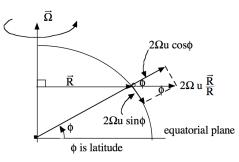
$$\left(\Omega + \frac{u}{R}\right)^2 \vec{R}$$

Note: velocity = angular velocity  $\times$  radius, so angular velocity = velocity/radius

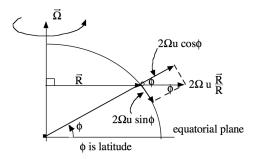




- Coriolis force in this scenario is directed radially outward from the axis of rotation.
- Coriolis has no component in latitudinal directions and projects into the meridional and vertical directions.







 Associated with this Coriolis force are the following acceleration components:

$$\left. \frac{dv}{dt} \right|_{\text{Coriolis}} = -2\Omega u \sin \phi \qquad \left. \frac{dw}{dt} \right|_{\text{Coriolis}} = 2\Omega u \cos \phi$$

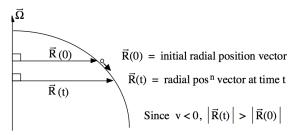


$$\left. \frac{dv}{dt} \right|_{\text{Coriolis}} = -2\Omega u \sin \phi \qquad \left. \frac{dw}{dt} \right|_{\text{Coriolis}} = 2\Omega u \cos \phi$$

- u > 0 (eastward): acceleration is toward the south and upward (upward Coriolis force is weak compared to gravity and slightly lessens the apparent weight of an object)
- u < 0 (westward): acceleration is toward the north and downward (slightly increases the apparent weight of an object)
- In either case, the Coriolis force is perpendicular to the direction of motion.
- In either case, we get a deflection to the left relative to the direction of motion.



• Imagine that we kick an initially resting mass m toward the south (v < 0)

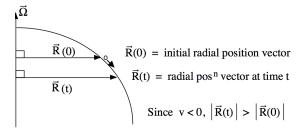


• From the conservation of angular momentum:

 $\left[ u(t) + \Omega R(t) \right] R(t) = C$ 

• Initial conditions will help us solve C.





• At the time of the kick (t = 0), u(0) = 0, and R = R(0):  $[0 + \Omega R(0)] R(0) = C \rightarrow C = \Omega R^2(0)$ 

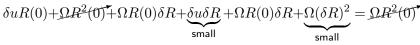
Thus,

$$[u(t) + \Omega R(t)] R(t) = \Omega R^2(0)$$



• A short time after the kick  $(t = \delta t)$  the mass is at radius  $R(0) + \delta R$  with a southward velocity (v < 0). u? (we will call it  $\delta u$  since we expect that it will be small for small  $\delta t$ 

$$\{\delta u + \Omega [R(0) + \delta R]\} [R(0) + \delta R] = \Omega R^2(0)$$

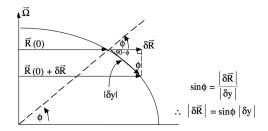


So, we neglect  $\delta u \delta R$  and  $\Omega (\delta R)^2$ 

$$\delta u R(0) + 2\Omega R(0) \delta R = 0 \rightarrow \delta u = -2\Omega \delta R$$

- The mass develops a small westward (easterly) velocity component.
- Let's describe the acceleration.





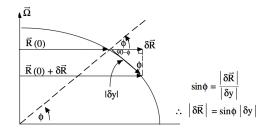
•  $\delta R = -\sin\phi\delta y$  (negative since  $\delta y$  corresponds to a postive  $\delta R$  (and reverse).

$$\delta u = -2\Omega \delta R = -2\Omega(-\sin\phi\delta y) = 2\Omega\sin\phi\delta y$$

Divide by  $\delta t$  and take the limit as  $\delta t \rightarrow 0$ 

$$\left.\frac{du}{dt}\right|_{\rm Coriolis} = 2\Omega\sin\phi\frac{dy}{dt} = 2\Omega v\sin\phi$$





- For our initial southward kick (v < 0),  $du/dt|_{\mathsf{Coriolis}} < 0$
- u is initially 0 but becomes negative
- This means that we get a deflection toward the west (right, relative to the direction of motion)
- We get the same formula and rightward deflection if the ball is kicked north.



- Imagine that we kick an initially resting mass m upward (w > 0) or downward (w < 0).
- Conservation of angular momentum leads to:

$$\frac{du}{dt}|_{\rm Coriolis} = -2\Omega w\cos\phi$$

 This is derived following a similar approach as for the horizontal components of momentum.



• Putting the all together:

$$\begin{split} &\frac{du}{dt}|_{\text{Coriolis}} = 2\Omega v \sin \phi - 2\Omega w \cos \phi \\ &\frac{dv}{dt}|_{\text{Coriolis}} = -2\Omega u \sin \phi \\ &\frac{dw}{dt}|_{\text{Coriolis}} = 2\Omega u \cos \phi \end{split}$$

• These terms must appear as apparent forces per unit mass to allow the application of  $\vec{F} = m\vec{a}$ .

